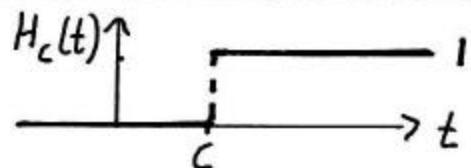


5.5 Discontinuous Forcing Functions

Heaviside step function ($c \geq 0$)

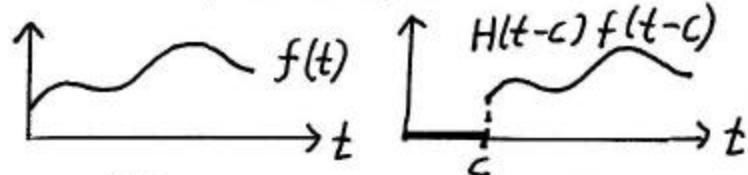


$$H_c(t) \equiv H(t-c) = \begin{cases} 1 & \text{for } t \geq c \\ 0 & \text{for } t < c \end{cases}$$

Since we restrict to $t \geq 0$, identify

$$H_0(t) \equiv H(t) = 1 \quad (\text{int } t \geq 0)$$

t -shift property of \mathcal{L} :



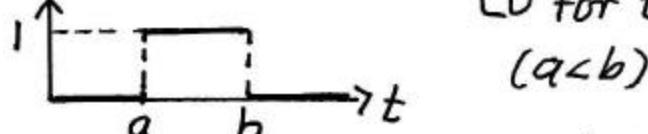
$$\mathcal{L}\{H(t-c)f(t-c)\} = e^{-cs} F(s)$$

$$\text{or } \mathcal{L}^{-1}\{e^{-cs} F(s)\} = H(t-c)f(t-c)$$

$$\Rightarrow \mathcal{L}\{H_c(t)\} = e^{-cs} \mathcal{L}(1) = \frac{e^{-cs}}{s}$$

Boxcar (Interval) function

$$H_{ab}(t) = H_a(t) - H_b(t) = \begin{cases} 0 & \text{for } t < a \\ 1 & \text{for } a \leq t < b \\ 0 & \text{for } t \geq b \end{cases}$$



$$\mathcal{L}\{H_{ab}(t)\}(s) = (e^{-as} - e^{-bs})/s$$

Piecewise Defined Functions

$$\text{Ex. 1: } g(t) = \begin{cases} 2t & \text{for } 0 \leq t < 1 \\ 2 & \text{for } 1 \leq t < \infty \end{cases}$$

Use boxcars:

$$\begin{aligned} g(t) &= 2t[1 - H(t-1)] + 2H(t-1) \\ &= 2t - 2H(t-1)(t-1) \end{aligned}$$

$$\begin{aligned} \Rightarrow \mathcal{L}(g)(s) &= 2\mathcal{L}\{t\}(s) - 2\mathcal{L}\{H(t-1)(t-1)\} \\ &= 2/s^2 - 2e^{-s} \mathcal{L}\{t\}(s) \\ &= 2/s^2 - 2e^{-s}/s^2 \end{aligned}$$

Inverse L-Transforms of Functions with Exponential Terms

$$\text{Ex. 2: } \mathcal{L}^{-1}\left\{\frac{e^{-s}}{s^2(s^2+1)}\right\}(t) \\ = \mathcal{L}^{-1}\left\{\frac{1}{s^2(s^2+1)}\right\}(t-1)$$

$$F(s) \equiv \frac{1}{s^2(s^2+1)} = \frac{1}{s^2} - \frac{1}{s^2+1}$$

$$\Rightarrow \mathcal{L}^{-1}\{e^{-s}F(s)\}(t) \\ = \mathcal{L}^{-1}\{1/s^2\}(t-1) + \mathcal{L}^{-1}\left\{\frac{1}{s^2+1}\right\}(t-1) \\ = H(t-1)[t-1 - \sin(t-1)]$$

$$\Rightarrow y(t) = -\sin t + 2t[1-H(t-1)] + 2H(t-1)[1+\sin(t-1)] \\ = (2t-\sin t)[1-H(t-1)] + [2+2\sin(t-1)-\sin t]H(t-1)$$

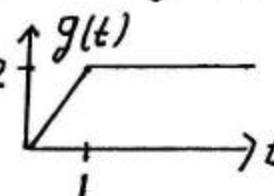
$$= \begin{cases} 2t - \sin t & \text{for } 0 \leq t < 1 \\ 2 + 2\sin(t-1) - \sin t & \text{for } t \geq 1 \end{cases} \quad (\text{see text, p. 221, for graph})$$

IVP's with Discontinuous Forcings

$$\text{Ex. 3: } y'' + y = g(t), y(0) = 0, y'(0) = 1$$

$$g(t) = \begin{cases} 2t & \text{for } 0 \leq t < 1 \\ 2 & \text{for } t \geq 1 \end{cases}$$

(as in Ex. 1)



$$\mathcal{L}(y'' + y) = (s^2 + 1)y - 1$$

$$\mathcal{L}(g) = 2(1 - e^{-s})/s^2 \quad (\text{from Ex. 1})$$

$$\Rightarrow (s^2 + 1)y - 1 = 2(1 - e^{-s})/s^2$$

$$\Rightarrow y(s) = \frac{1}{s^2+1} + \frac{2}{s^2(s^2+1)} - \frac{2e^{-s}}{s^2(s^2+1)}$$

$$\Rightarrow y(t) = \sin t + 2(t - \sin t) \\ - 2H(t-1)[t-1 - \sin(t-1)] \quad (\text{Ex. 2})$$

5.6 The Delta Function

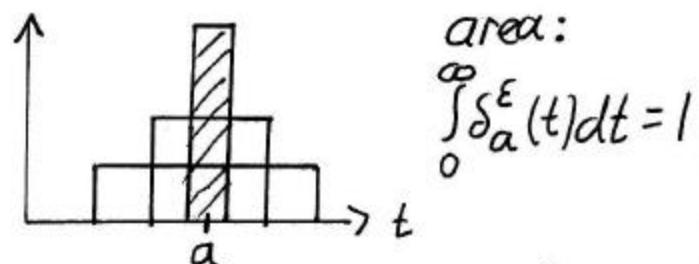
$F(t)$ force \Rightarrow

$$I = \int_a^b F(t) dt = \text{momentum change in } a \leq t \leq b \\ = \underline{\text{impulse}}$$

$$mv' = F(t) \rightarrow I = mv(b) - mv(a)$$

unit impulse in $a - \varepsilon/2 \leq t \leq a + \varepsilon/2$:

$$\delta_a^\varepsilon(t) = \begin{cases} 1/\varepsilon & \text{for } a - \varepsilon/2 \leq t < a + \varepsilon/2 \\ 0 & \text{else} \end{cases} \\ = \frac{1}{\varepsilon} [H_{a-\varepsilon/2}(t) - H_{a+\varepsilon/2}(t)]$$



$$\text{Def.: } \delta_a(t) \equiv \delta(t-a) = \lim_{\varepsilon \rightarrow 0} \delta_a^\varepsilon(t)$$

Think of $\delta_a(t)$ "=". $\begin{cases} \infty & \text{for } t=a \\ 0 & \text{for } t \neq a \end{cases}$

$$\text{s.t. } \int_{a-\eta}^{a+\eta} \delta_a(t) dt = 1 \text{ for any } \eta > 0$$

$\delta_a(t)$ describes effect
of "unit hammer"

"filter property":

$$\int_0^\infty \delta_a(t) \phi(t) dt = \phi(a)$$

for any continuous fct. $\phi(t)$

$$\Rightarrow \mathcal{L}(\delta_a)(s) = \int_0^\infty e^{-st} \delta_a(t) dt = e^{-sa}$$

Impulse Response:

$$\left. \begin{aligned} e'' + ae' + be &= \delta(t) \\ e(0) = 0, e'(0) = 0 \end{aligned} \right\} (*)$$

(more precisely: $e(0-) = 0, e'(0-) = 0$)

$$\text{Let } E(s) = \mathcal{L}(e)(t)$$

$$\Rightarrow (s^2 + as + b)E = 1$$

Thm.: For $t > 0$ the solution of
(*) coincides with the solution of
 $y'' + ay' + by = 0, y(0) = 0, y'(0) = 1$

5.7 Convolutions

Consider $F(s), G(s)$. Question: $\mathcal{L}^{-1}\{F(s)G(s)\} = ?$

Ex.: $F(s) = G(s) = \frac{1}{s} \Rightarrow \mathcal{L}^{-1}(FG) = \mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\} = t$

But $\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = 1 \Rightarrow \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = 1 \neq t$

Thm.: $\mathcal{L}^{-1}\{F(s)G(s)\}(t) = \int_0^t f(\tau)g(t-\tau)d\tau$ where $f = \mathcal{L}^{-1}(F), g = \mathcal{L}^{-1}(G)$

Def.: Given $f(t), g(t)$, the convolution of f and g is:

$$(f * g)(t) = \int_0^t f(\tau)g(t-\tau)d\tau$$

Properties: $f * g = g * f, (f * \delta_a)(t) = f(t-a)H(t-a)$

System Response: $y'' + ay' + by = f(t), y(0) = 0 = y'(0)$

$$\text{Apply } \mathcal{L} \Rightarrow (s^2 + as + b)y = F(s)$$

$$\Rightarrow Y(s) = \frac{1}{s^2 + as + b} F(s) = E(s) F(s)$$

$$\text{where } E(s) = 1/(s^2 + as + b)$$

$$\Rightarrow y(t) = (e * f)(t) \text{ where } e(t) = \mathcal{L}^{-1}(E)(t) = \begin{array}{l} \text{"unit response"} \\ \text{= response to } f(t) = \delta(t) \end{array}$$